# Computer Science 294 Lecture 20 Notes

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March 23, 2023

## 1 Hardness of Approximation

### 1.1 Constraint statisfaction problems

**Definition 1.1.** A constraint satisfaction problem (CSP) over domain  $\Omega$  is defined by a finite set of predicates  $\Psi$  where each  $\psi \in Psi$  is some constraint  $\psi : \Omega^r \to \{0,1\}$ . The arity of a CSP is the maximal arity r of a predicate in  $\Psi$ .

**Example 1.1.** Max-3SAT, Max-Cut, Max-3LIN, and Max-3Coloring are al CSPs.

All these problems are NP-hard.

**Example 1.2.** In Max-3SAT,  $\Omega = \{T, F\}$ , and a predicate could be something like  $\psi(v_1, v_2, v_3) = v_1 \wedge v_2 \wedge v_3$  or  $\psi(v_1, v_2, v_3) = \overline{v_1} \wedge v_2 \wedge \overline{v_3}$ . The arity is 3.

**Definition 1.2.** An instance P for MAxCSP( $\Psi$ ) over variable set V is a list of tuples: (scope, predicate)  $C = (s, \psi)$ , where  $\psi \in \Psi$  and  $s = (v_1, \ldots, v_r)$  is a typle of variables in V.

**Definition 1.3.** An assignment for an instance P is a labeling  $F: V \to \Omega$ . F satisfies a constraint  $(s, \psi)$  if  $\psi(F(s)) = 1$ , where  $F(s) = (F(v_1), \dots, F(v_r))$ .

**Definition 1.4.** The value pf F on P, is the fraction of constraints in P satisfied by F. That is,

$$\operatorname{Val}_p(F) = \mathbb{E}_{(S,\psi) \sim P}[\psi(F(S))].$$

The optimal value is

$$OPT(P) := \max_{F} Val_{P}(F).$$

Last time, we discussed string testers. The main insight is that CSPs are the same as string testers. Here is a dictionary between CSPs and string testing.

CSP instance $P$	string tester
Assignment $F:[n] \to \Omega$	$\omega \in \Omega^n$
Value of F	$\mathbb{P}(\text{tester accepts }\omega)$
$\Psi$	predicates you apply in the string tester
number of constraints	2 <sup>#</sup> random bits

**Example 1.3.** Take Max-3SAT, for example. We think of the string as an assignment to all the variables. Our queries ask for the value of 3 bits in the string, and the predicates are the predicates of the DNF, things like  $x_1 \wedge \overline{x_2} \wedge x_3$ .

**Definition 1.5.** An  $(\alpha, \beta)$ -approximation algorithm for MaxxCSP( $\Psi$ ) is an algorithm that on instances where whose best assignment has value  $\geq \beta$ , the algorithm is guaranteed to output and assignment with value  $\geq \alpha$ .

**Example 1.4.** (1,1) approximating Max-Cut is easy because this is the case where the graph is bipartite.

**Example 1.5.** (1/2, 0.51) approximating Max-Cut is easy because if we randomly cut each edge with probability 1/2, we will cut half the edges on average.

**Example 1.6.** (1, 1)-approximating MaxSAT is NP-hard because if we can find a satisfying assignment for any formula which can be satisfied, then we can solve 3SAT.

**Example 1.7.** (1,1)-approximating MaxColoring is NP-hard because solving this problem would allow us to solve 3Coloring.

**Example 1.8.** (1,1)-approximating Max-3LIN is easy because we can just use Gaussian elimination to see whether a system of linear equations has a solution.

However, the following theorem tells us that Gaussian elimination is not robust for solving this CSP.

**Theorem 1.1** (Håstad). (0.51, 0.99)-approximating Max-3LIN is NP-hard.

**Theorem 1.2** (PCP theorem).  $(1 - \delta_0, 1)$ -approximating Max-3SAT is NP-hard.

However, you can use a randomized algorithm (and then de-randomize it) to show the following.

**Proposition 1.1.** (7/8, 1)-approximating Max-3SAT is easy.

**Theorem 1.3** (Håstad). For all constants  $\delta > 0$ ,  $(7/8 + \delta, 1)$ -approximating Max-3SAT is NP-hard.

<sup>&</sup>lt;sup>1</sup>You can remember which variable is which by  $\beta$ est and  $\alpha$ lgorithm.

#### 1.2 Testing for dictators vs no notable coordinates

Håstad's idea was that to prove hardness for  $\text{MaxCSP}(\Psi)$ , it suffices to design a "relaxed" dictator test that only uses predicates from  $\Psi$ . By relaxed, we mean that it is enough to make a test which rejects with "decent" probability when f is "very far" from being all dictators.

Recall that

$$\operatorname{Inf}_{i}^{(\rho)}(f) := \operatorname{Stab}_{\rho}(F_{i}f) = \sum_{S \supset i} \rho^{|S|-1} \widehat{f}(S)^{2}.$$

Qualitatively, we think of this as a "noisy influence."

#### **Definition 1.6.** The total annotated influence is

$$\mathbb{I}^{(\rho)} := \sum_{i=1}^{n} \operatorname{Inf}_{o}^{(\rho)}(f)$$
$$= \sum_{S \neq \varnothing} |S| \rho^{|S|-1} \widehat{f}(S)^{2}$$
$$= \sum_{k=1}^{n} k \rho^{k-1} W^{k}(f).$$

**Lemma 1.1.** For all  $0 < \rho < 1$  and for all  $k, k\rho^{k-1} \le \frac{1}{1-\rho}$ .

This tells us that

$$\mathbb{I}^{(\rho)}(f) \le \frac{\rho}{1-\rho}.$$

**Definition 1.7.** We sat that a coordinate j is  $\varepsilon$ -notable if  $\operatorname{Inf}_{j}^{(1-\varepsilon)}(f) \geq \varepsilon$ .

**Example 1.9.** If  $f = \chi_i$ , then  $\operatorname{Inf}_i^{(\rho)}(f) = 1$ .

**Example 1.10.** If 
$$f = PARITY_n = \chi_{[n]}$$
, then  $Inf_i^{(\rho)}(f) = \rho^{n-1}$ .

Even though these are both characters, once we apply noise,  $\chi_i$  has influence 1 and the parity function has exponentially small influence.

**Example 1.11.** If f is a O(1)-junta, then it has a notable coordinate.

**Definition 1.8.** An  $(\alpha, \beta)$ -Dictator-vs-No-Notable-Coordinates test using  $\Psi$  is a function tester that for all  $n \in \mathbb{N}$  can be applied to functions  $f : \{\pm 1\}^n \to \{\pm 1\}$  and

- makes at most r queries to f and applies a preducate from  $\Psi$ .
- If f is a dictator, then  $\mathbb{P}(\text{tester accepts } f) \geq \beta$ .

• For all small enough  $\varepsilon > 0$ , if f has no  $\varepsilon$ -notable coordinates, then

$$\mathbb{P}(\text{tester accepts } f) \leq \alpha + \lambda(\varepsilon), \quad \text{where } \lambda(\varepsilon) \xrightarrow{\varepsilon \to 0} 0.$$

**Theorem 1.4.** Suppose there exists an  $(\alpha, \beta)$ -Dictator-vs-No-Notable-Coordinates test using  $\Psi$ . Then for all  $\varepsilon > 0$ ,  $(\alpha + \varepsilon, \beta - \varepsilon)$ -approximating MaxCSP( $\Psi$ ) is Unique-Games-hard. In other words, there exists a polynomial time reduction so that a YES instance for the Unique Games problem is mapped to an Instance with Val  $\geq \beta - \varepsilon$  and so that a NO instance for the Unique Games problem is mapped to an Instance with Val  $\leq \alpha + \varepsilon$ .

**Example 1.12.** The **Unique Games** $(q, \delta)$  **problem** is a CSP with domain  $\Omega = \{0, 1, \dots, q-1\}$  and constraints like  $x_7 - x_5 \equiv 3 \pmod{9}$  or  $x_5 - x_{11} \equiv 2 \pmod{9}$ . In YES instances, a  $1 - \delta$  fraction of the constraints can be satisfied simultaneously. In a No instance, any assignment satisfies a  $\leq \delta$  fraction of the constraints.

Conjecture 1.1 (Unique games conjecture). For all  $\delta > 0$ , there exists a  $q \in \mathbb{N}$  such that  $UG(q, \delta)$  is NP-hard.

Håstad made a test based on the idea of BLR lienarity testing.

**Theorem 1.5** (Håstad). For all  $\delta > 0$ , there is a  $(1/2, 1 - \delta)$ -Dictator-vs-No-Notable-Coordinates test using 3LIN equations (such as  $x_i \oplus x_j \oplus x_k \equiv 6 \pmod{2}$ ). The test is

- Pick  $X, Y \sim \{\pm 1\}^n$  uniformly at random.
- Pick a bit  $B \sim \{\pm 1\}$  uniformly at random
- Let  $Z \in \{\pm 1\}^n$  be defined as  $Z_i = X_i \cdot Y_i \cdot B$ .
- Take  $Z' \sim N_{1-\delta}(Z)$
- Query f(X), f(Y), f(Z) and accept iff  $f(X) \cdot f(Y) \cdot f(Z') = B$ .

In particular,

$$\mathbb{P}(tester\ accepts\ f) = \frac{1}{2} + \frac{1}{2} \sum_{|S|\ odd} \widehat{f}(S)^3 (1 - \delta)^{|S|}.$$

In  $\mathbb{F}_2$  notation, the predicate we are checking is a linear equation:  $F(x)+F(y)+f(z)\equiv 0 \pmod{2}$ , where  $f(x)=(-1)^{F(x)}$ . With z', this is a noisy linear equation.

Notice that if  $f = \chi_i$  is a dictator, then

$$\mathbb{P}(\text{tester accepts}) = \frac{1}{2} + \frac{1}{2}(1 - \delta) = 1 - \frac{\delta}{2}.$$

*Proof.* We want to calculate

$$\mathbb{P}(\text{tester accepts}) = \frac{1}{2} + \frac{1}{2} \mathbb{E}_{X,Y,Z',B}[f(X)f(Y)f(Z')B].$$

Look at

$$\mathbb{E}_{X,Y,Z',B}[f(X)f(Y)f(Z')B \mid B=1] = \mathbb{E}[f(X)f(Y)\mathbb{E}_{Z'\sim N_{1-\delta}(X\cdot Y)}[f(Z')]]$$

$$= \mathbb{E}[f(X)f(\underbrace{Y}_{X\cdot Z})T_{1-\delta}f(\underbrace{X\cdot Y}_{Z})]$$

$$= \mathbb{E}_{Z}[\mathbb{E}_{X}[f(X)f(X\cdot Z)]T_{1-\delta}f(Z)]$$

$$= \mathbb{E}_{Z}[(f*f)(Z)T_{1-\delta}f(Z)]$$

Using Plancherel's theorem,

$$= \sum_{S} \widehat{f * f}(S) (1 - \delta)^{|S|} \widehat{f}(S)$$
$$= \sum_{S} \widehat{f}(S)^{3} (1 - \delta)^{|S|}.$$

The same calculation with B = -1 gives

$$\mathbb{E}_{X,Y,Z',B}[f(X)f(Y)f(Z')B \mid B=1] = \sum_{S} \widehat{f}(S)^{3} (-(1-\delta))^{|S|}.$$

So we get We want to calculate

$$\mathbb{P}(\text{tester accepts}) = \frac{1}{2} + \frac{1}{4} \left( \mathbb{E}[f(X)f(Y)f(Z')B \mid B = 1] + \mathbb{E}[f(X)f(Y)f(Z')B \mid B = -1] \right)$$

$$= \frac{1}{2} + \frac{1}{2} \sum_{S:|S| \text{ odd}} \widehat{f}(S)^3 (1 - \delta)^{|S|}.$$

Now we can check that if  $\varepsilon < \delta$  and f has no  $\varepsilon$ -notable coordinates, then

$$\begin{split} \mathbb{P}(\text{tester accepts } f) &= \frac{1}{2} + \frac{1}{2} \sum_{S:|S| \text{ odd}} \widehat{f}(S)^3 (1-\delta)^{|S|} \\ &\leq \frac{1}{2} + \frac{1}{2} \max_{S:|S| \text{ odd}} \cdot \sum_{S} \widehat{f}(S)^2 \\ &\leq \frac{1}{2} + \frac{1}{2} \sqrt{\max_{S:|S| \text{ odd}} \widehat{f}(S)^2 (1-\delta)^{|S|-1}} \\ &\leq \frac{1}{2} + \frac{1}{2} \sqrt{\max_{i} \text{Inf}_i^{(1-\delta)}(f)} \\ &\leq \frac{1}{2} + \frac{1}{2} \sqrt{\max_{i} \text{Inf}_i^{(1-\varepsilon)}(f)} \\ &\leq \frac{1}{2} + \frac{1}{2} \sqrt{\varepsilon}. \end{split}$$